# Series A58 Absolute – Parallel Output



As machine position control systems strive

able to incorporate a feedback device which

for higher and higher performance, being

substantial benefit. Dynapar brand Series

absolute position rather than incremental

the presence of electrical noise. System

A58 encoders provide a unique data output

for each resolvable shaft position. By using

count data, the shaft position can always be

known, even after power interruptions or in

design can be simplified because there is no need to perform a reference cycle or return to

home function to determine the true machine

Single turn devices are offered with resolu-

tion ranging from .5° (720 counts per rev) to

14 bit (16,384 counts per rev). For applica-

Parallel output formats are available in binary

tions which require travel over extended distances, multi-turn models can provide

unique position outputs for each shaft position up to 4096 rotations.

provides exact position data can be of

- Single or Multi-turn versions
- Resolution up to 14 Bit (single turn) and 24 Bit (multi-turn)
- Parallel output
- Short Circuit Protected

This product has been discontinued. Please contact Dynapar for assistance. 1-800-873-8731 www.dynapar.com

## **SPECIFICATIONS**

#### **Mechanical**

Shaft Size: 6mm syncro flange, 10 mm clamping flange

Shaft Loading: 10 mm: 24 lbs axial, 35 lbs radial; 6 mm: 13 lbs axial, 24 lbs radial

Shaft Tolerance: +0/-0.0007 Starting Torque: ≤0.2 in-oz Weight: 11 oz. (300 g.) Shaft Speed: 6,000 RPM

Shaft Speed: 6,000 RPM

## <u>Environmental</u>

Operating Temperature: -25° to 85°C Storage Temperature: -25° to +85°C Shock: 100 G's for 3 msec duration Vibration: 10 to 500 Hz @ 10 G's Enclosure Rating: IP67

#### Electrical - Parallel Outputs

Accuracy ± 1/2 LSB (± 1 LSB above 12 bit) Power Requirements: 5 VDC ±5% or 10-30V; 200 mA maximum

**Code:** Absolute; natural binary or Gray Code **Data Output:**  $\pm$ 30 mA, short circuit protected **Control Inputs:** Active low,  $\leq$ 20% of V<sub>(IN)</sub>;

- Inactive high, open or ≥70% of V<sub>(IN)</sub> Latch Input: Data outputs change with shaft position when high or open; data outputs inhibited from changing when low. Available only for models with 12 bit and below resolution
- Direction Input: Count up for CW shaft rotation when high or open; count down for CW shaft rotation when low. Available only for models with 13 bit and below resolution
- Frequency Response: 100 kHz maximum

#### **Electrical Connections**

Table 1 – Single Turn							
14 bit	13 Bit	12 Bit	10 Bit	Color			
SO (LSB)	N.C.	N.C.	N.C.	Grey/Pink			
S1	SO (LSB)	N.C.	N.C.	Brown/Yellow			
S2	S1	SO (LSB)	N.C.	Brown/Grey			
S3	S2	S1	N.C.	Red/Blue			
S4	S3	S2	SO (LSB)	Violet			
S5	S4	S3	S1	White/Brown			
S6	S5	S4	S2	White/Green			
S7	S6	S5	S3	White/Yellow			
S8	S7	S6	S4	White/Grey			
S9	S8	S7	S5	White/Pink			
S10	S9	S8	S6	White/Blue			
S11	S10	S9	S7	White/Red			
S12	S11	S10	S8	White/Black			
S13msb)	S12(MSB)	S11(MSB)	S9 (MSB)	Brown/Green			
	Yellow						
	Pink						
	Green						
	Black						
	Red						
	Brown						

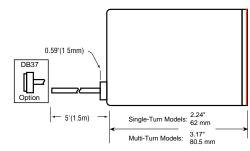
Table 2 – Multi-Turn							
Signal	Color	Pin	Signal	Color	Pin		
S0	Brown	2	M4	White/Blue	14		
S1	Green	21	M5	Brown/Blue	33		
S2	Yellow	3	M6	White/Red	15		
S3	Grey	22	M7	Brown/Red	34		
S4	Pink	4	M8	White/Black	16		
S5	Violet	23	M9	Brown/Black	35		
S6	Grey/Pink	5	M10	Grey/Green	17		
S7	Red/Blue	24	M11	Yellow/Grey	36		
S8	White/Green	6	Alarm	Pink/Green	18		
S9	Brown/Green	25	Direction	Yellow/Pink	10		
S10	White/Yellow	7	Latch	Green/Blue	30		
S11	Yellow/Brown	26	Enable	Yellow/Blue	12		
M0	White/Grey	8	10-30 VDC	Red	13		
M1	Grey/Brown	27	10-30 VDC	White	31		
M2	White/Pink	9	Common	Blue	1		
M3	Pink/Brown	28	Common	Black	20		

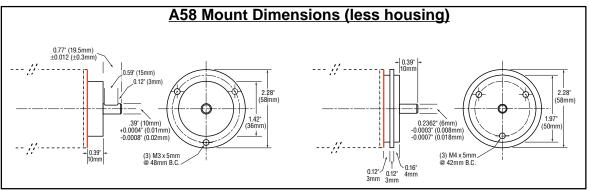
position.

or gray code.



# A58 Housing Dimensions (less mount)





## **Ordering Information**

To order, complete the model number with code numbers from the table below:

Code 1: Model	Code 2: CP	R Co	de 3: Mechanical	Code 4: Interface	Code 5: Electrical	Code 6: Termination	
<b>A58</b>							
	Ordering Information						
A58 58mm Absolute encoder, Parallel Output	0720 720 coun rev** 1024 1024 cou rev (10 bi 4096 4096 cou rev (12 bi 8192 8192 cou rev(13 bii 0014 16,384 cc rev (14 bi 1212 4096 cou rev, multi (24 bit)	nts/ 1 t) nts/ t) nts/ :) punts/ t) nts/	Face mount 10mm shaft Servo mount 6mm shaft	<ul> <li>Parallel- Binary (push- pull)</li> <li>Parallel-Gray code (push- pull)</li> </ul>	<ul> <li>0 5 VDC input power</li> <li>1 10 - 30 VDC input power (must be ordered for multi- turn models*)</li> </ul>	<ul> <li>0 End Exit Cable</li> <li>2 End exit cable w/ DB37 male connector (must be ordered for multi-turn models*)</li> </ul>	

\* Code 2: 1024, 4096, 8192, 0014 = single-turn 1212 = multi-turn \*\* Utilizes excess gray code

# Series A58 Absolute – Bus Output



- Single or Multi-turn versions
- Resolution up to 14 Bit (single turn) and 26 Bit (multi-turn)
- Choice of 3 bus networks
- Short Circuit Protected

As machine position control systems strive for higher and higher performance, being able to incorporate a feedback device which provides exact position data can be of substantial benefit. Dynapar brand Series A58 encoders provide a unique data output for each resolvable shaft position. By using absolute position rather than incremental count data, the shaft position can always be known, even after power interruptions or in the presence of electrical noise. System design can be simplified because there is no need to perform a reference cycle or return to home function to determine the true machine position.

Single turn devices are offered with resolution ranging from .5° (720 counts per rev) to 14 bit (16,384 counts per rev). For applications which require travel over extended distances, multi-turn models can provide unique position outputs for each shaft position up to 4096 rotations.

Choice of bus network which can significantly reduce wiring, enhance diagnostics and reduce total installed cost.

## **SPECIFICATIONS**

#### <u>Mechanical</u>

Shaft Size: 6mm syncro flange, 10 mm clamping flange

Shaft Loading: 10 mm: 24 lbs axial, 35 lbs radial; 6 mm: 13 lbs axial, 24 lbs radial Shaft Tolerance: +0/-0.0007

Starting Torque: ≤0.2 in-oz Weight: 11 oz. (300 g.) Shaft Speed: 6,000 RPM

#### Environmental

Operating Temperature: -25° to +85°C Storage Temperature: -25° to +85°C Shock: 100 G's for 3 msec duration Vibration: 10 to 500 Hz @ 10 G's Enclosure Rating: IP67

## Electrical - DeviceNet

Accuracy: ± 1/2 LSB (± 1 LSB above 12 bit) Power Requirements: 10 - 30 VDC; 200 mA maximum

Code: Binary

Current for feed through supply: 3 Amp Interface: CAN High Speed per ISO/DIS

11898, CAN specification 2.0 B **Protocol:** DeviceNet according to Rev. 2.0 programmable encoder

Update Rate: 5 ms

Baud Rate: DIP switch selectable 125, 250, 500 Kbps

MAC ID: DIP switch settable

#### Electrical - Profibus

Accuracy  $\pm$  1/2 LSB ( $\pm$  1 LSB above 12 bit)

Power Requirements: 10 - 30 VDC 200 mA maximum

- Code: Binary
- Current for feed through supply: 2 Amp
- Interface: RS-485
- Protocol: Profibus DP w/class 2 encoder profile
- Baud Rate: Automatically set by master between 9.6 Kbps and 12 Mbps
- Device Address: DIP switch settable
- Programmable Functions: direction, resolution per rev, total resolution, preset

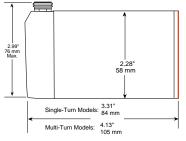
#### Electrical - Interbus

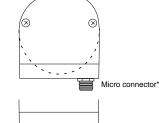
Accuracy: ± 1/2 LSB (± 1 LSB above 12 bit) Power Requirements: 10 - 30 VDC 200 mA maximum Code: Binary Interface: RS-485 for remote bus Protocol: Interbus w/ ENCOM profile K3 Update Rate: 600 μs Baud Rate: 500 Kbps Programmable functions: direction, scaling factor, preset, offset

Absolute Encoders



# A58 Housing Dimensions (less mount)







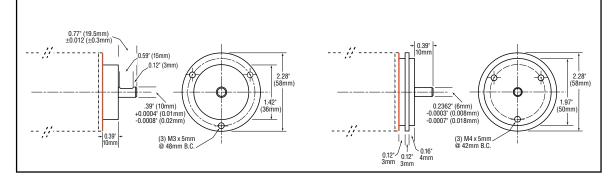
Micro Connector: Simple plug-in connection from a "T" drop off the DeviceNet trunk line

## \* Industrial Bus Interfaces

Integrated Manifold: Provides direct in and out connection to bus trunk line

Integrated manifold\*

# A58 Mount Dimensions (less housing)



### Ordering Information

		To order, c		number with code n	umbers from the table below:	
Code 1: Model		Code 2: CPR	Code 3: Mechanical	Code 4: Interface	Code 5: Electrical	Code 6: Termination
<b>A58</b>						
			1	Ordering Information	1	1
A58 58mm Absolute encoder	1024 4096 8192 0014 1212 1213 1214	1024 counts/ rev (10 bit) 4096 counts/ rev (12 bit) 8192 counts/ rev(13 bit) 16,398 counts/ rev (14 bit) 4096 counts/ rev, multiturn (24 bit) 8192 counts/ rev, multiturn (25 bit) 16,384 counts/ rev, multiturn (26 bit)	<ul> <li>0 Face mount 10mm shaft</li> <li>1 Servo mount 6mm shaft</li> </ul>	<ul> <li>D DeviceNet</li> <li>P Profibus</li> <li>I Interbus</li> </ul>	1 10 - 30 VDC input power	M Integrated bus manifold available when code 4 = D E 5 pin Micro connector <sup>‡</sup>
				Accessories		
ACAB-F90MS ACAB-F90MS ACAB-F90FS ACAB-F90FS ACON-MFF	S2 5p 1 5p 2 5p	in DeviceNet cabl in DeviceNet cabl in DeviceNet cabl	e, female 90°, male s e, female 90°, female	traight, 1 meter, Micro traight, 2 meters, Micro straight, 1 meter, Micr straight, 2 meters, Mic	o connector o connector	

ABSOLUTE ENCODERS