# Series A58 Absolute - Parallel Output 

- Single or Multi-turn versions
- Resolution up to 14 Bit (single turn) and 24 Bit (multi-turn)
- Parallel output
- Short Circuit Protected

This product has been discontinued.<br>Please contact Dynapar for assistance. 1-800-873-8731<br>www.dynapar.com

As machine position control systems strive for higher and higher performance, being able to incorporate a feedback device which provides exact position data can be of substantial benefit. Dynapar brand Series A58 encoders provide a unique data output for each resolvable shaft position. By using absolute position rather than incremental count data, the shaft position can always be known, even after power interruptions or in the presence of electrical noise. System design can be simplified because there is no need to perform a reference cycle or return to home function to determine the true machine position.
Single turn devices are offered with resolution ranging from $.5^{\circ}$ ( 720 counts per rev) to 14 bit ( 16,384 counts per rev). For applications which require travel over extended distances, multi-turn models can provide unique position outputs for each shaft position up to 4096 rotations.
Parallel output formats are available in binary or gray code.

## SPECIFICATIONS

## Mechanical

Shaft Size: 6 mm syncro flange, 10 mm clamping flange
Shaft Loading: 10 mm : 24 lbs axial, 35 lbs radial; $6 \mathrm{~mm}: 13 \mathrm{lbs}$ axial, 24 lbs radial
Shaft Tolerance: $+0 /-0.0007$
Starting Torque: $\leq 0.2$ in-oz
Weight: 11 oz . ( 300 g .)
Shaft Speed: 6,000 RPM

## Environmental

Operating Temperature: $-25^{\circ}$ to $85^{\circ} \mathrm{C}$
Storage Temperature: $-25^{\circ}$ to $+85^{\circ} \mathrm{C}$
Shock: 100 G's for 3 msec duration
Vibration: 10 to 500 Hz @ 10 G's
Enclosure Rating: IP67

## Electrical - Parallel Outputs

Accuracy $\pm 1 / 2$ LSB ( $\pm 1$ LSB above 12 bit)
Power Requirements: 5 VDC $\pm 5 \%$ or $10-30 \mathrm{~V}$; 200 mA maximum
Code: Absolute; natural binary or Gray Code
Data Output: $\pm 30 \mathrm{~mA}$, short circuit protected
Control Inputs: Active low, $\leq 20 \%$ of $\mathrm{V}_{(\mathbb{N})}$; Inactive high, open or $\geq 70 \%$ of $\mathrm{V}_{\text {(IN }}$
Latch Input: Data outputs change with shaft position when high or open; data outputs inhibited from changing when low. Available only for models with 12 bit and below resolution
Direction Input: Count up for CW shaft rotation when high or open; count down for CW shaft rotation when low. Available only for models with 13 bit and below resolution
Frequency Response: 100 kHz maximum

Electrical Connections

| Table 1 - Single Turn |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| 14 bit | 13 Bit | 12 Bit | 10 Bit | Color |
| S0 (LSB) | N.C. | N.C. | N.C. | Grey/Pink |
| S1 | S0 (LSB) | N.C. | N.C. | Brown/Yellow |
| S2 | S1 | S0 (LSB) | N.C. | Brown/Grey |
| S3 | S2 | S1 | N.C. | Red/Blue |
| S4 | S3 | S2 | S0 (LSB) | Violet |
| S5 | S4 | S3 | S1 | White/Brown |
| S6 | S5 | S4 | S2 | White/Green |
| S7 | S6 | S5 | S3 | White/Yellow |
| S8 | S7 | S6 | S4 | White/Grey |
| S9 | S8 | S7 | S5 | White/Pink |
| S10 | S9 | S8 | S6 | White/Blue |
| S11 | S10 | S9 | S7 | White/Red |
| S12 | S11 | S10 | S8 | White/Black |
| S13mSB) | S12(MSB) | S11(MSB) | S9 (MSB) | Brown/Green |
| Tristate |  |  |  | Yellow |
| Latch (binary only) |  |  |  | Pink |
| Direction |  |  |  | Green |
| Common |  |  |  | Black |
| $5 \mathrm{~V} / 10-30$ VDC |  |  |  | Red |
| $\overline{\text { Alarm }}$ |  |  |  | Brown |


| Table 2 - Multi-Turn |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Signal | Color | Pin | Signal | Color | Pin |
| S0 | Brown | 2 | M4 | White/Blue | 14 |
| S1 | Green | 21 | M5 | Brown/Blue | 33 |
| S2 | Yellow | 3 | M6 | White/Red | 15 |
| S3 | Grey | 22 | M7 | Brown/Red | 34 |
| S4 | Pink | 4 | M8 | White/Black | 16 |
| S5 | Violet | 23 | M9 | Brown/Black | 35 |
| S6 | Grey/Pink | 5 | M10 | Grey/Green | 17 |
| S7 | Red/Blue | 24 | M11 | Yellow/Grey | 36 |
| S8 | White/Green | 6 | $\overline{\text { Alarm }}$ | Pink/Green | 18 |
| S9 | Brown/Green | 25 | Direction | Yellow/Pink | 10 |
| S10 | White/Yellow | 7 | $\overline{\text { Latch }}$ | Green/Blue | 30 |
| S11 | Yellow/Brown | 26 | Enable | Yellow/Blue | 12 |
| M0 | White/Grey | 8 | $10-30$ VDC | Red | 13 |
| M1 | Grey/Brown | 27 | $10-30$ VDC | White | 31 |
| M2 | White/Pink | 9 | Common | Blue | 1 |
| M3 | Pink/Brown | 28 | Common | Black | 20 |

## A58 Housing Dimensions (less mount)



## A58 Mount Dimensions (less housing)



Ordering Information
To order, complete the model number with code numbers from the table below:

| Code 1: Model | Code 2: CPR | Code 3: Mechanical | Code 4: Interface | Code 5: Electrical | Code 6: Termination |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A58 | $\square \square$ | $\square$ | $\Gamma$ |  | $\square$ |
| Ordering Information |  |  |  |  |  |
| A58 58mm Absolute encoder, Parallel Output | 0720 720 counts/ <br> rev** <br> 1024 1024 counts/ <br>  rev (10 bit) <br> 4096 <br>  4096 counts/ <br> rev (12 bit)  <br> 8192 8192 counts/ <br>  rev(13 bit) <br> 0014 <br>  16,384 counts/ <br> rev (14 bit)  <br> 1212 4096 counts/ <br>  rev, multiturn <br> (24 bit)  | 0 Face mount 10 mm shaft <br> 1 Servo mount 6 mm shaft | 0 ParallelBinary (pushpull) <br> 1 Parallel-Gray code (pushpull) | 05 VDC input power <br> 1 10-30 VDC input power (must be ordered for multiturn models*) | 0 End Exit Cable <br> 2 End exit cable w/ DB37 male connector (must be ordered for multi-turn models*) |

* Code 2: 1024, 4096, 8192, 0014 = single-turn

1212 = multi-turn
** Utilizes excess gray code

## Series A58 Absolute - Bus Output



As machine position control systems strive for higher and higher performance, being able to incorporate a feedback device which provides exact position data can be of substantial benefit. Dynapar brand Series A58 encoders provide a unique data output for each resolvable shaft position. By using absolute position rather than incremental count data, the shaft position can always be known, even after power interruptions or in the presence of electrical noise. System design can be simplified because there is no need to perform a reference cycle or return to home function to determine the true machine position.
Single turn devices are offered with resolution ranging from $.5^{\circ}$ ( 720 counts per rev) to 14 bit (16,384 counts per rev). For applications which require travel over extended distances, multiturn models can provide unique position outputs for each shaft position up to 4096 rotations.
Choice of bus network which can significantly reduce wiring, enhance diagnostics and reduce total installed cost.

## SPECIFICATIONS

## Mechanical

Shaft Size: 6 mm syncro flange, 10 mm clamping flange
Shaft Loading: 10 mm : 24 lbs axial, 35 lbs radial; 6 mm : 13 lbs axial, 24 lbs radial
Shaft Tolerance: $+0 /-0.0007$
Starting Torque: $\leq 0.2$ in-oz
Weight: $11 \mathrm{oz} .(300 \mathrm{~g}$.
Shaft Speed: 6,000 RPM

## Environmental

Operating Temperature: $-25^{\circ}$ to $+85^{\circ} \mathrm{C}$
Storage Temperature: $-25^{\circ}$ to $+85^{\circ} \mathrm{C}$
Shock: 100 G's for 3 msec duration
Vibration: 10 to 500 Hz @ 10 G's
Enclosure Rating: IP67

## Electrical - DeviceNet

Accuracy: $\pm 1 / 2$ LSB ( $\pm 1$ LSB above 12 bit)
Power Requirements: 10-30 VDC;
200 mA maximum
Code: Binary
Current for feed through supply: 3 Amp
Interface: CAN High Speed per ISO/DIS
11898, CAN specification 2.0 B
Protocol: DeviceNet according to Rev. 2.0
programmable encoder
Update Rate: 5 ms
Baud Rate: DIP switch selectable 125, 250, 500 Kbps
MAC ID: DIP switch settable

## Electrical - Profibus

Accuracy $\pm 1 / 2$ LSB ( $\pm 1$ LSB above 12 bit)
Power Requirements: 10-30 VDC 200 mA maximum
Code: Binary
Current for feed through supply: 2 Amp
Interface: RS-485
Protocol: Profibus DP w/class 2 encoder profile
Baud Rate: Automatically set by master between 9.6 Kbps and 12 Mbps
Device Address: DIP switch settable
Programmable Functions: direction, resolution per rev, total resolution, preset

## Electrical - Interbus

Accuracy: $\pm 1 / 2$ LSB ( $\pm 1$ LSB above 12 bit)
Power Requirements: 10-30 VDC
200 mA maximum
Code: Binary
Interface: RS-485 for remote bus
Protocol: Interbus w/ ENCOM profile K3
Update Rate: $600 \mu \mathrm{~s}$
Baud Rate: 500 Kbps
Programmable functions: direction, scaling factor, preset, offset

A58 Housing Dimensions (less mount)


## 7/, $\quad$ Industrial Bus Interfaces

Micro Connector: Integrated Manifold: Simple plug-in connection from a "T" drop off the DeviceNet trunk line

A58 Mount Dimensions (less housing)


Ordering Information
To order, complete the model number with code numbers from the table below:

| Code 1: Model |  | Code 2: CPR | Code 3: Mechanical | Code 4: Interface |  | Code 5: Electrical | Code 6: Termination |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| A58 |  |  | $\square$ | $\square$ |  | $\square$ | $\square$ |
| Ordering Information |  |  |  |  |  |  |  |
| A58 58mm Absolute encoder | $1024$ | 1024 counts/ rev (10 bit) | 0 Face mount 10 mm shaft <br> 1 Servo mount 6 mm shaft | D DeviceNet <br> P Profibus <br> I Interbus |  | 10-30 VDC input power | M Integrated bus manifold |
|  | $\begin{array}{\|ll} 4096 & 4096 \text { counts/ } \\ & \text { rev (12 bit) } \end{array}$ |  |  |  |  |  | available when code $4=\mathrm{D}$ <br> E 5 pin Micro connector ${ }^{\ddagger}$ |
|  | $8192$ | 8192 counts/ rev(13 bit) |  |  |  |  |  |
|  | 0014 | 16,398 counts/ rev (14 bit) |  |  |  |  |  |
|  | $1212$ | 4096 counts/ rev, multiturn (24 bit) |  |  |  |  |  |
|  | $1213$ | 8192 counts/ rev, multiturn (25 bit) |  |  |  |  |  |
|  | 1214 16,384 counts/ rev, multiturn (26 bit) |  |  |  |  |  |  |
| Accessories |  |  |  |  |  |  |  |
| ACAB-F90MS1 5 pin DeviceNet cable, female $90^{\circ}$, male straight, 1 meter, Micro connector ACAB-F90MS2 5 pin DeviceNet cable, female $90^{\circ}$, male straight, 2 meters, Micro connector ACAB-F90FS1 5 pin DeviceNet cable, female $90^{\circ}$, female straight, 1 meter, Micro connector ACAB-F90FS2 5 pin DeviceNet cable, female $90^{\circ}$, female straight, 2 meters, Micro connector ACON-MFF DeviceNet splitter, male, female, female |  |  |  |  |  |  |  |
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