TECHNICAL DATA

AM34 - Absolute Multiturn Motor Feedback Encoder
Standard Performance for Servo Motor and Drive

- Low-profile absolute multiturn encoder for standard and functional safety motion control
- Very compact absolute multiturn encoder with mounting depth less than 20 mm
- High Resolution 12 bit up to 22 bit Singleturn + 12 bit Multiturn
- Digital BiSS-C, SSI interface
- This encoder is available with functional safety (SIL2 PLd, SIL3 PLe, category 3), safety version has separate datasheet D-582-049
- Wide operating temperature range up to +120°C
- Speed up to 12 000 rpm - without self-heating due to bearing less design
- Electronic Data Sheet (EDS) - Motor and drive data can be stored inside encoder
- Encoder temperature sensor *(BiSS-C)*

TECHNICAL DATA
mechanical

Housing diameter	38 mm
Shaft	cone 1:3 - M4 screw, 6 mm hub shaft - M3 or M4 screw
Mounting depth	20 mm, with plug ≤22 mm
Mounting flange	Direct flange/shaft mount
Protection class shaft input	IP20
Protection class housing	IP20
Axial endplay of mating shaft	±0.5 mm max. @ nominal position
Max. speed	12 000 rpm
Starting torque typ.	n/a
Moment of inertia	0.4 kgmm² (rotor with screw M4 x 30)
Max. angular acceleration	250.000 rad/sec²
Vibration resistance (DIN EN 60068-2-6)	300 m/s² (10 … 2 000 Hz) 100 m/s² (10 … 2 000 Hz) min.
Shock resistance (DIN EN 60068-2-27)	3000 m/s² (6 ms)
Material shaft	Stainless steel
Material housing / cover	Aluminum / plastic
Weight	50g
Connection (with strain relief)	ECU Interface - PCB connector axial
Operating temperature [1]	-40°C ... +120°C (E = 7-30V +115°C)
Storage temperature	-30°C ... +80°C

[1] see measuring point M1, dimensional drawings page 4.

TECHNICAL DATA

AM34 - Absolute Multiturn Motor Feedback Encoder
Standard Performance for Servo Motor and Drive

TECHNICAL DATA
electrical

General design	as per EN IEC 61010-1, protection class III, contamination level 2, overvoltage class II
Supply voltage	5 V DC +10%/-5%, GND / 7-30V DC
Power consumption	*≤0.6 W (typical 0.4 W)*
Resolution singleturn **other resolution on request*	12 Bit, 14 Bit, 16 Bit - standard performance 18 Bit - advanced performance 20 Bit, 22 Bit - high performance
Resolution multiturn	12 Bit multiturn - mechanical gear box
Resolution incremental signals	Standard: 256 periods sine+cosine *(SinCos)* Inc. AB: 1-4096 ppr *(TTL)*
Electrical Interface	RS422 - BiSS-C or SSI *(Clock, Data),* 1Vpp - sine+cosine *(SinCos);* TTL - AB incremental
Data Protocol	BiSS-C / SSI gray / SSI binary
Electronic Data Sheet (EDS)	512 bytes of storage for encoder data
OEM Memory	*Additional storage for motor-, drive data (BiSS-C)*
Absolute accuracy (typ.)	±0.033° / ±2' / ±120'' *(after autocalibration[2])*
Repeatability (typ.)	±0.0055° / ±0.33' / ±20'' *(after autocalibration[2])*

[2] follow the instructions in the manual D-582-037 for automatic adjustment features on command (see BiSS-C encoder adjustment)

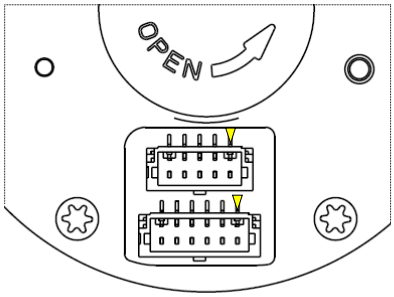
TECHNICAL DATA
features

Cycle time *(Frame Repetition)*	≥ > 30 µsec
Propagation delay /latency	*≤ 0.25 µsec*
Signal stabilization	Signal stabilization by auto-gain with monitoring
Compensation of misalignment	Automated adjustment during installation
Commutation	Adjustable zero position

TECHNICAL DATA

AM34 - Absolute Multiturn Motor Feedback Encoder
Standard Performance for Servo Motor and Drive

ELECTRICAL CONNECTIONS
SSI / BiSS-C / Incremental



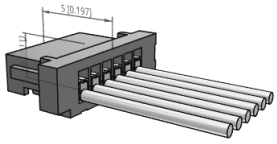
PCB-Connector[2]					
Type	**T1M-06-GF-S-V-K-TR**		*Type*	**T1M-05-GF-S-V-K-TR**	
PIN	*Signal SSI / BiSS-C (absolute)*		*PIN*	*Signal 1Vpp or TTL (incremental)*	
1	**VDD**		1	**B+**	*(COS+ or B+)*
2	**GND**		2	**B-**	*(COS– or B-)*
3	**DATA-**	*(RS422)*	3	**GND**	
4	**DATA+**	*(RS422)*	4	**A+**	*(SIN+ or A+)*
5	**CLOCK–**	*(RS422)*	5	**A-**	*(SIN– or A-)*
6	**CLOCK+**	*(RS422)*			

Pin assignment to interface signal

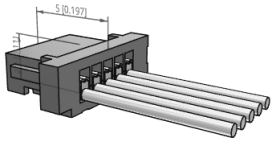
Insulation resistance according to EN IEC 60204-1 PELV/SELV
[2] SAMTEC T1M / ISS1 / S1SST

ACCESSORIES
Connection Cables

Connection cable - SSI / BiSS-C / Incremental	Part Nr.
Absolute signals cable, 20 cm, 6-pin (S1SST-06-28-GF-08.00-S)	3 561 128
Incremental signals cable, 20 cm, 5-pin (S1SST-05-28-GF-08.00-S)	3 561 127



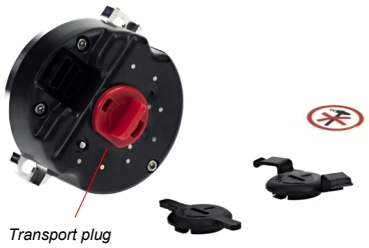
3 561 128 S1SST-06-28-GF-08.00-S
monochrome (all wires are blue)



3 561 127 S1SST-05-28-GF-08.00-S
monochrome (all wires are blue)

Plug Options

Connection cable / Plug	Part Nr.
Sticker to close the cap	E2531169
Plug to close the cap	E2545059
Plug with wire guides to close the cap	E2545052

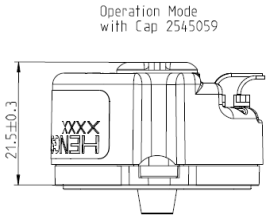


E2531169

E2545059

E2545052

Plug dimensions



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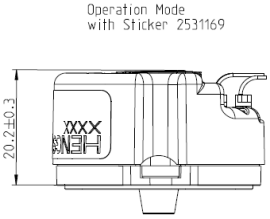
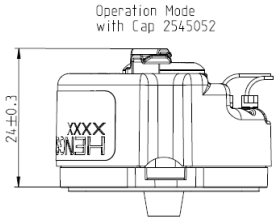
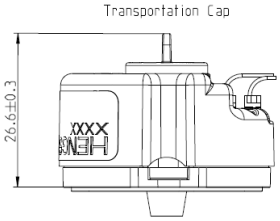


E2531169



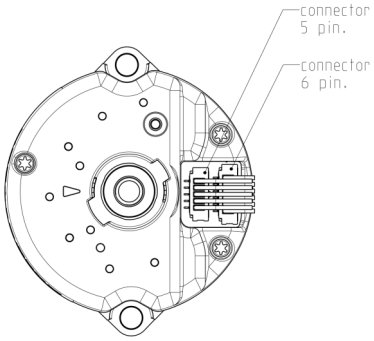
E2545052

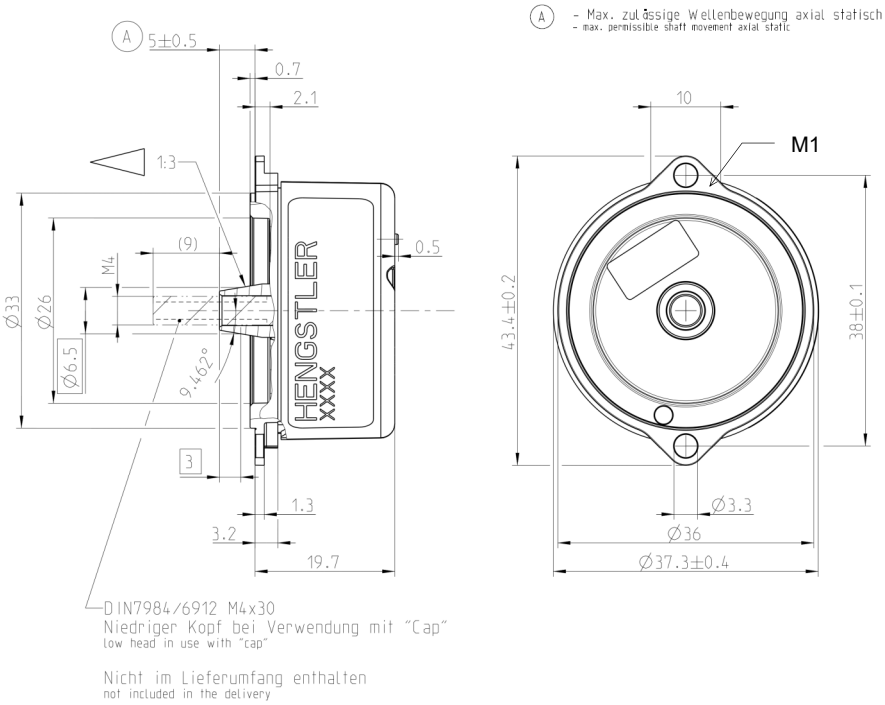


AM34 - Absolute Multiturn Motor Feedback Encoder
Standard Performance for Servo Motor and Drive

DIMENSIONAL DRAWINGS

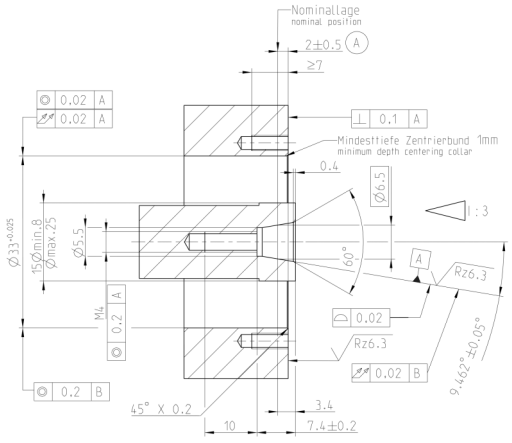
Z0.T, 8 mm shaft, cone 1:3, D38/C33, M4 screw

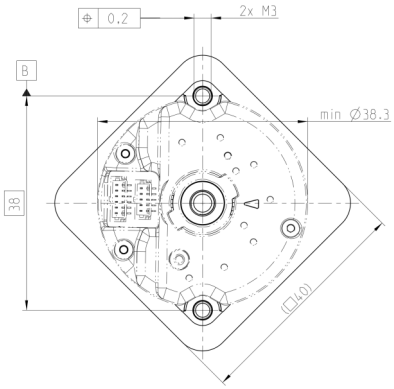


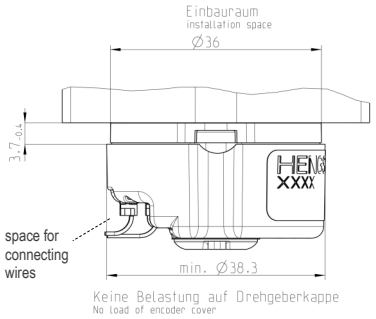


INSTALLATION REQUIREMENTS

Z0.T, 8 mm shaft, cone 1:3, D38/C33, M4 screw







Note: space for connecting wires are considered at the encoder. With a small bending radius (max. R2.7), the connection remain within the encoder outer contour.

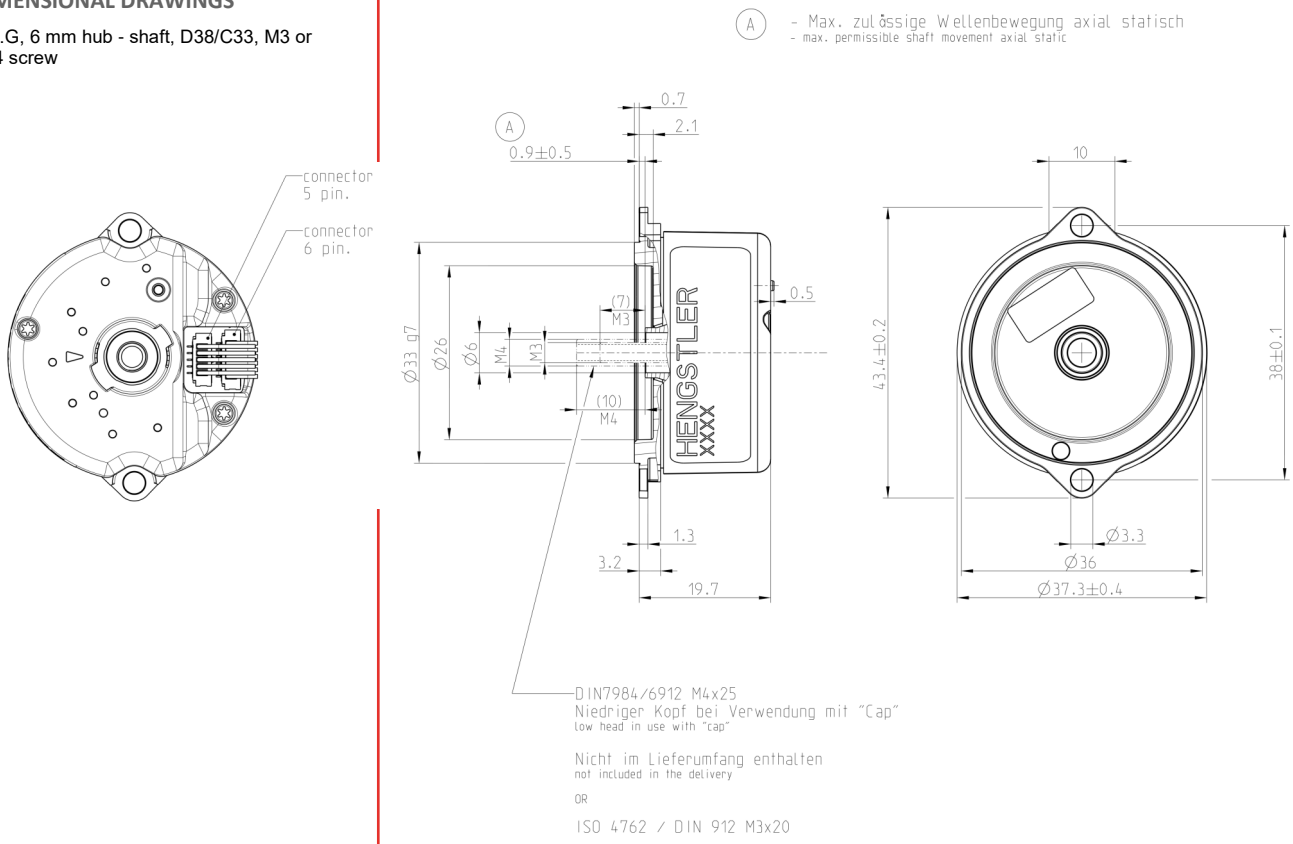
Dimensions in mm
Tolerances according DIN ISO 2768-m

TECHNICAL DATA

AM34 - Absolute Multiturn Motor Feedback Encoder
Standard Performance for Servo Motor and Drive

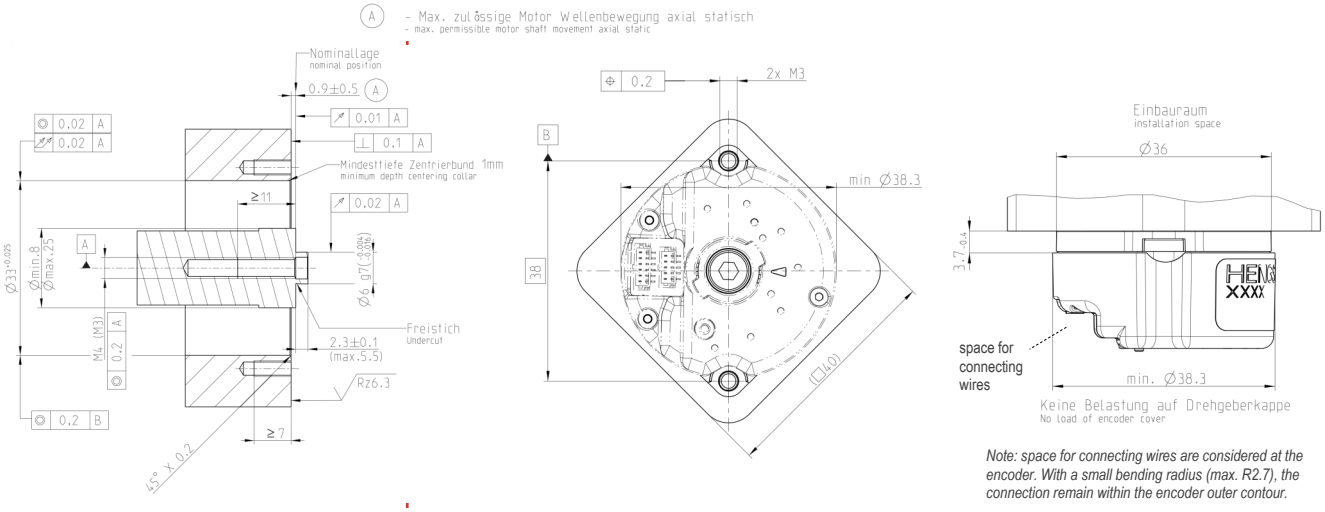
DIMENSIONAL DRAWINGS

Z0.G, 6 mm hub - shaft, D38/C33, M3 or M4 screw



INSTALLATION REQUIREMENTS

Z0.G, 6 mm hub - shaft, D38/C33, M3 or M4 screw



Note: space for connecting wires are considered at the encoder. With a small bending radius (max. R2.7), the connection remain within the encoder outer contour.

Dimensions in mm
Tolerances according DIN ISO 2768-m

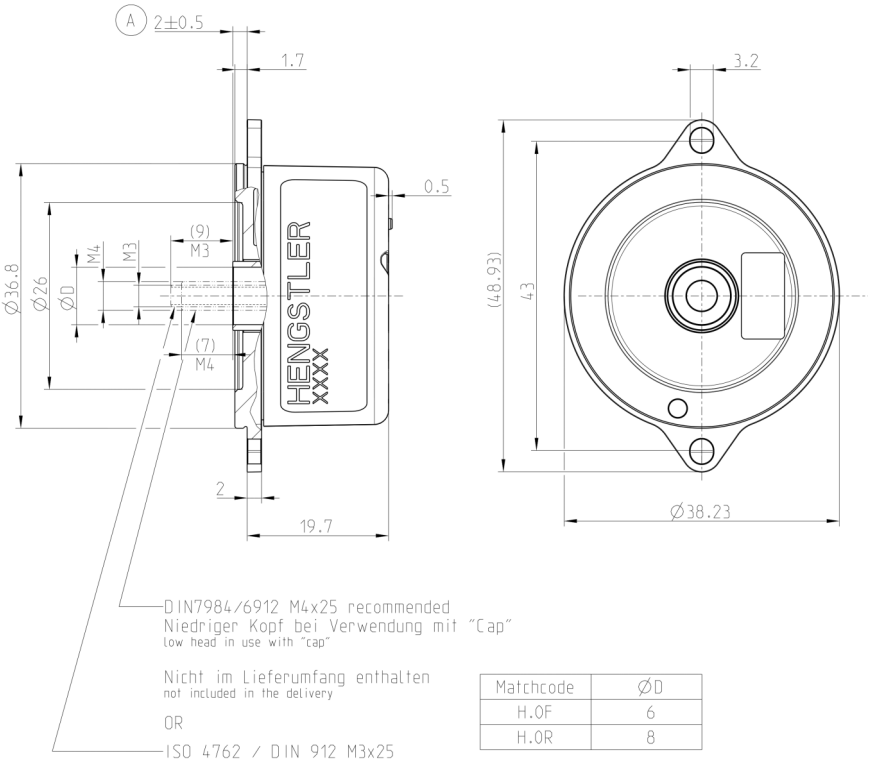
Specifications subject to change without notice.

TECHNICAL DATA

AM34 - Absolute Multiturn Motor Feedback Encoder
Standard Performance for Servo Motor and Drive

DIMENSIONAL DRAWINGS

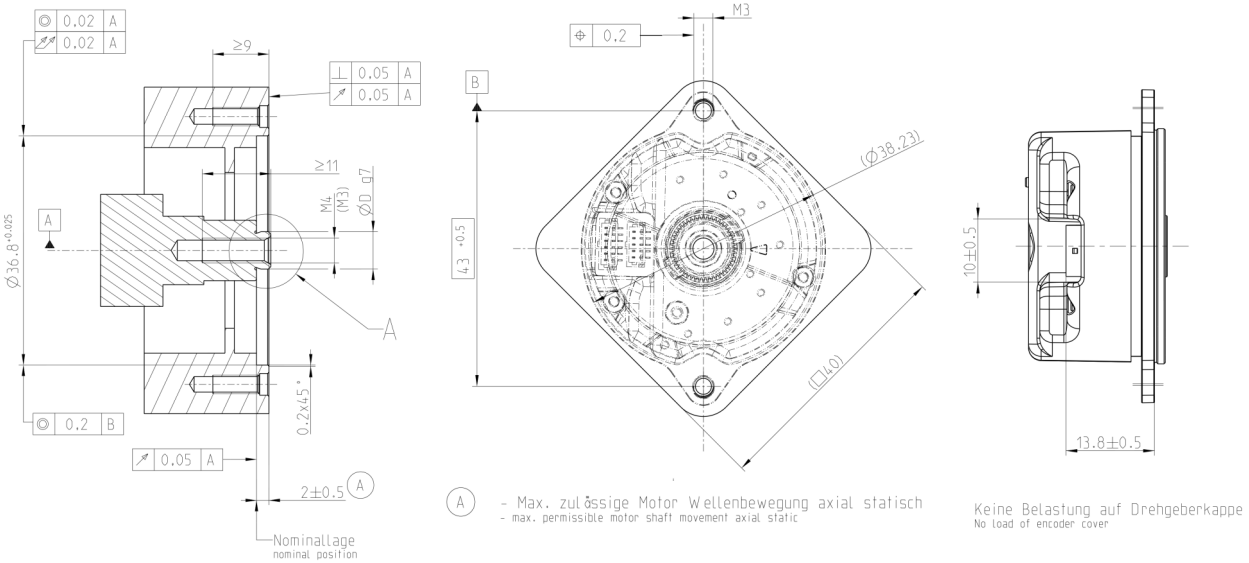
H0.R, 8 mm hub-shaft, D43/C36.8, M3 or M4 screw

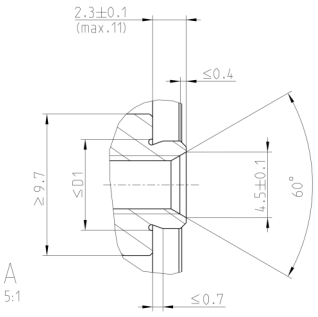


Matchcode	ØD
H.0F	6
H.0R	8

INSTALLATION REQUIREMENTS

H0.R, 8 mm hub-shaft, D43/C36.8, M3 or M4 screw





Matchcode	ØD g7	D1
H.0F	6	6.5
H.0R	8	8.5

Dimensions in mm
Tolerances according DIN ISO 2768-m

Specifications subject to change without notice.

AM34 - Absolute Multiturn Motor Feedback Encoder
Standard Performance for Servo Motor and Drive

ORDERING INFORMATION

Type[3]	Resolution[4]	Supply voltage	Flange, Protection, Shaft	Interface[5]	Connection
AM34/ AM34S AM34E	**0012** 12 Bit ST 0013 13 Bit ST **0014** 14 Bit ST 0015 15 Bit ST **0016** 16 Bit ST 0017 17 Bit ST **0018** 18 Bit ST 0019 19 Bit ST **0020** 20 Bit ST 0022 22 Bit ST **1212** 12 Bit ST + 12 Bit MT 1213 13 Bit ST + 12 Bit MT **1214** 14 Bit ST + 12 Bit MT 1215 15 Bit ST + 12 Bit MT **1216** 16 Bit ST + 12 Bit MT 1217 17 Bit ST + 12 Bit MT **1218** 18 Bit ST + 12 Bit MT 1219 19 Bit ST + 12 Bit MT **1220** 20 Bit ST + 12 Bit MT 1222 22 Bit ST + 12 Bit MT	**A** 5 VDC **E** 7-30 VDC[6]	**Z.0T** 2-eared flange D38/ C33, IP20, 8 mm cone-shaft 1:3, M4 **Z.0G** 2-eared flange, IP20 D38/C33, 6 mm hub-shaft, M3 or M4 H.0R 2-eared flange, IP20, D43/C36.8, 8 mm hub -shaft, M3 or M4	**BE** BiSS-C **BU** BiSS-C + SinCos 1Vpp **SG** SSI gray **SU** SSI gray + SinCos 1Vpp **SB** SSI binary **ST** SSI binary + SinCos 1Vpp **BZ** BiSS-C + A/B TTL **SZ** SSI gray + A/B TTL **SY** SSI binary + A/B TTL	**4** Absolute signals & power supply, 6 pole connector, axial Incremental signals, 5 pole connector, axial (available according to interface)

[3] Type: AM34/: Standard
AM34S: Functional Safety (SIL2, PLd) - *on request, see separate datasheet for safety version*
AM34E: Functional Safety (SIL3, PLe) - *on request,, see separate datasheet for safety version*

[4] Other resolution on request

[5] Analog Sin/Cos signals (256 periods sine + cosine)
Incremental A/B signals TTL (0001 to 4096 ppr), resolution is specified at the end of product code behind vertical bar symbol "|" (e.g. "|4096" or "|0512")
Other interface on request
[grey] Color coded version on request

[6] Power Supply 7-30V only till +115°C

TECHNICAL MANUALS

Documentation	Ordering code
Installation Instructions, English	D-582-034
Assembly Instructions, English	D-582-037
Software	**Ordering code**
AM34 Service Tool - for configuration and calibration	On request

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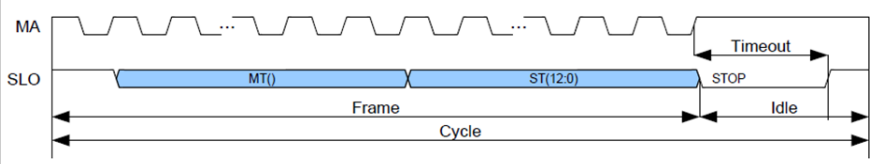
E-Mail: info@hengstler.com Internet: www.hengstler.com

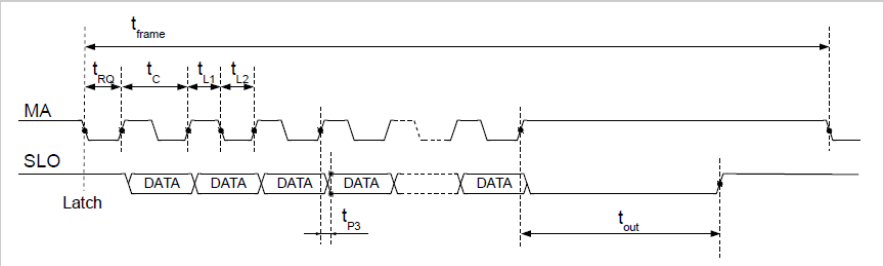
AM34 - Absolute Multiturn Motor Feedback Encoder
Standard Performance for Servo Motor and Drive

TECHNICAL DATA
electrical interface SSI

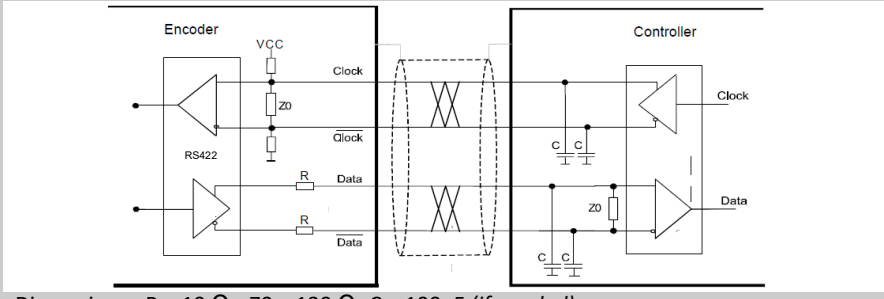
Standard SSI Protocol Frame	
Bit Length	**Description**
0 or 12	Multiturn position
14, 16, 18, 20 or 22	Singleturn position
SSI gray	Code



SSI Timing				
Symbol	**Parameter**	**Min.**	**Max.**	**Unit**
t_{frame}	Permissible Frame Repetition	30	unlimited	µs
$1/t_C$	Permissible Clock Frequency	0.1	1	MHz
t_{L1}	Clock Signal hi Level Duration	250	t_{OUT}	ns
t_{L2}	Clock Signal lo Level Duration	250	t_{OUT}	ns
t_{RQ}	REQ Signal lo Level Duration	50		ns
t_{OUT}	Slave Timeout	16	24	µs
t_{P3}	Propagation Delay *(SLO stable after MA lo→hi)*	60	250	ns



Recommended input circuit Standard SSI or BiSS-C to 10 MHz clock rate



Dimensions: R = 10 Ω , Z0 = 120 Ω, C = 100pF *(if needed)*

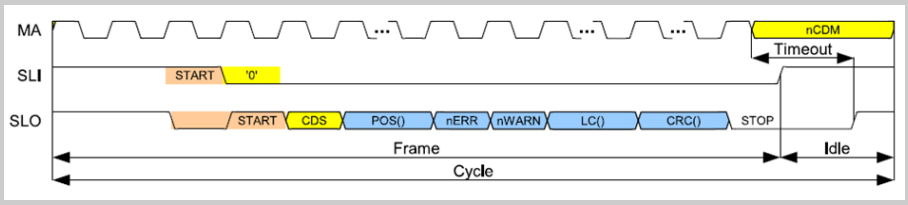
Cable Length[1]	**SSI Clock Frequency**	**BiSS-C Clock Frequency***
< 25 m	< 1 MHz	< 10 MHz
< 50 m	< 400 kHz	< 10 MHz
< 100 m	< 300 kHz	< 10 MHz
< 200 m	< 200 kHz	**Details for BiSS-C see page 6 ff.*
< 400 m	< 100 kHz	

[1] *Twisted pair wiring with ground shield on both sides recommended.*

AM34 - Absolute Multiturn Motor Feedback Encoder Standard Performance for Servo Motor and Drive

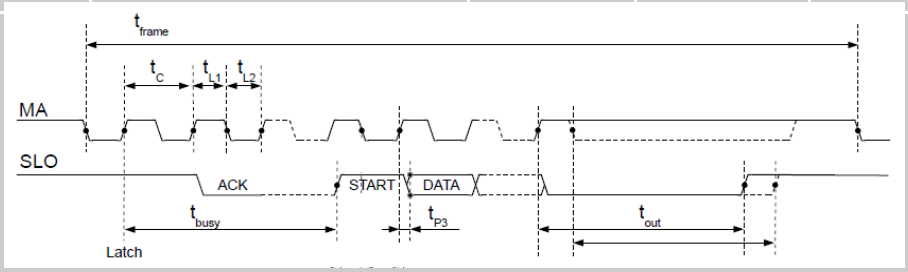
BiSS-C Protocol Frame

Bit Length	Description
0 or 12	Multiturn position
14, 16, 18, 20 or 22	Singleturn position
1	Error bit nERR (active low)
1	Warning bit nWARN (active low)
0	Sign-of-life counter (LC)
6	CRC (6-bit CRC polynomial: $X^6 + X^1 + X^0$)

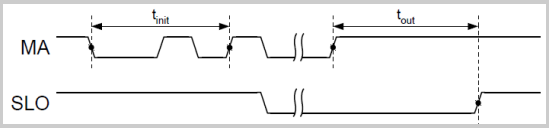


BiSS-C Timing

Symbol	Parameter	Min.	Max.	Unit
t_{frame}	Permissible Frame Repetition	30	unlimited	µs
$1/t_C$	Permissible Clock Frequency	0.1	10	MHz
t_{L1}	Clock Signal hi Level Duration	25	t_{OUT}	ns
t_{L2}	Clock Signal lo Level Duration	25	t_{OUT}	ns
t_{busy}	Processing Time with Start Bit Delay		6 t_C	ns
t_{OUT}	Adaptive Slave Timeout (t_{init} = 1.5 t_{MA}) *	0.1	24	µs
t_{P3}	Propagation Delay: SLO stable after MA lo→hi	60	250	ns



*Adaptive Slave Timeout:
(t_{init} measured as first 1.5 · t_{MA} each frame)



Art. No.: D-582-033
Edition: 3190326ED2

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TECHNICAL DATA

BiSS-C Interface
- Register assignment

Table of register assignment

Address (Hex)	Name	Size	Memo
0x00..0x3F	Registerbank	64 Bytes	
0x40	**Bankselection**	0..8 Bits (1 Byte)	1)
0x41	EDS-Bank	0..8 Bits (1 Byte)	1)
0x42..0x43	ProfileID	16 Bits (2 Bytes)	3)
0x44..0x47	Serialnumber	32 Bits (4 Byte)	3)
0x4E..0x4F	Temperature sensor	16 Bits (2 Bytes)	4)
0x77	Command register	0..8 Bits (1 Byte)	2)
0x78..0x7A	DeviceID	24 Bits (3 Bytes)	3)
0x7B..0x7D	Production Date	24 Bits (3 Bytes)	3)
0x7E..0x7F	ManufacturerID	16 Bits (2 Bytes)	3)

1) Bank selection e.g. for Encoder-Profile and BiSS-Identifier.
2) Supported commands see below.
3) The value is saved as a Big Endian, i.e. with the highest-value byte at the lowest-value address.
4) Temperature value [°C] = $XXXX_{(signed)}/10$

Bank selection
The bank selection register at address **0x40** selects a register bank consisting of up to 0x27 (39_{dec}) banks and displays these at the register addresses 0x00 to 0x3F.
- Bank 0x0E: Encoder-Profile and BiSS-Identifier; - Bank 0x24: EDS BiSS Interface data;
- Bank 0x25: EDS Encoder data; - Bank 0x26...0x27 OEM data

In order to send a **Command to the encoder**, the command (CMD) must be written into **register 0x77**.
Example for command "Preset": Write the value 0x88 (MTST_PRESET_STORE) to the address 0x77. This sets the total position value (single and multiturn) to 0.

BiSS-C Interface
- Commands

COMMANDS

CMD (7:0) Addr. 0x77; bit7:0 default: 0x00

Code	Name	Description
0x41	**CONF_WRITE_ALL**	Write current configuration of all banks to EEPROM. This includes the RPL information for all banks and the RPL information for the EEPROM. Valid CRC checksums are always calculated automatically beforehand for all banks.
0x88	**MTST_PRESET_STORE**	Identical to MTST_PRESET, additionally store the containing bank 0xB..C to EEPROM.
0x89	MT_PRESET_STORE	Identical to MT_PRESET, additionally store the containing bank 0xC to EEPROM.
0xB0	AUTO_ADJ_ANA	Automatic analog adjustment. -> Duration in seconds = 900/speed in rpm.
0xB2	AUTO_READJ_DIG	Automatic digital re-adjustment (in-field). -> Duration in seconds = 1200/speed in rpm.
0xB3	AUTO_ADJ_ECC	Automatic eccentricity adjustment. -> Duration in seconds = 15360/speed in rpm.
0xFF	<NOP_FAIL>	<Return-code: last operation failed>

(*) The active bank is defined by BSEL; BSEL must not be changed before the command finishes.

AM34 - Absolute Multiturn Motor Feedback Encoder Standard Performance for Servo Motor and Drive

TECHNICAL DATA
BiSS-C Identifier
Encoder-Profile

Encoder-Profil and BiSS-Identifier

Register	Value (HEX)	Category	Description
0x41	0x24	Profile	First Bank of Electronic Data Sheet (EDS)
0x42	0x62		BiSS Profile ID: Position Data
0x43	0xXX		BiSS Profile ID: Data with Error and Warning (w/o CRC) e.g. 12bit MT + 24bit ST + ErrorBit + WarningBit -> 38 bits => 0x26
0x44	0xXX		Serial number: 7 digits production identifier + 3 digits sequence number (max. 2^{32})
0x45	0xXX		
0x46	0xXX		
0x47	0xXX		
0x78	0xXX	BiSS Identifier	Encoder part number (max. 2^{32}) DeviceID: e.g. $0582001_{(DEC)}$ -> $08E171_{(HEX)}$
0x79	0xXX		
0x7A	0xXX		
0x7B	0xXX		Production date: Day (BCD format)
0x7C	0xXX		Production date: Month (BCD format)
0x7D	0xXX		Production date: Year (BCD format)
0x7E	0x48		Manufacturer ID: Hengstler -> "HE"$_{(ASCII)}$ = $4845_{(HEX)}$
0x7F	0x45		

Electronic Data Sheet (EDS)
- EDS BiSS Interface data

Bank 0x24: EDS BiSS Interface data

Register	Value	Units	Description
0x00	0x01		EDS version (continuous number)
0x01	0x02	Banks	EDS length (bank count completely)
0x02	0x26		Bank address USER start (bank selection in address 0x40, 255= not available)
0x03	0x27		Bank address USER end (bank selection address 0x40)
0x04	0x64	ns	Minimum permitted clock period on MA (TMA)
0x05	0x00	ns	Minimum BiSS timeout (0= adaptive) (BiSS time = reg(value)*250ns)
0x06	0x00	ns	Maximum BiSS timeout (0= adaptive) (BiSS time = reg(value)*250ns)
0x07	0x00	ns	Minimum BiSS timeout_S (0= adaptive) (BiSS time = reg(value)*25ns)
0x08	0x00	ns	Maximum BiSS timeout_S (0= adaptive) (BiSS time = reg(value)*25ns)
0x09	0x00		Minimum sampling period adaptive timeout (0= adaptive timeout not available)
0x0A	0x00		Maximum sampling period adaptive timeout (0= adaptive timeout not available)
0x0B	0x00		Minimum cycle time (0= no limitation)
0x0C	0x01	ns	Maximum processing time SCD
0x0D	0x00	TMA	Additional processing time SCD in clocks
0x0E...0x0F	0x0000	ms	Maximum "power on delay" until control communication is available
0x10	0x01		Number of data channel in this device (number of words)
0x11	0x01		Area of validity for this EDS (number of slave addresses)
0x12	0x00		Memory location for this EDS (slave ID within this device)
0x13	0x00		Reserved
0x14	0x26		Bank address for content description data channel 1 (profile EDS)
0x15	0xXX	bit	Data length data channel 1 (MT+ST+EW+LC+CRC)
0x16	0x02	bit	Data format data channel 1
0x17	0x43		CRC polynomial (8:1) for data channel 1
0x18	0x00		Bank address for content description data channel 2 (profile EDS)
0x19	0x00	bit	Data length data channel 2
0x1A	0x00	bit	Data format data channel 2
0x1B	0x00		CRC polynomial (8:1) for data channel 2
0x1C	0x00		Bank address for content description data channel 3 (profile EDS)
0x1D	0x00		Data length data channel 3
0x1E	0x00		Data format data channel 3
0x1F	0x00		CRC polynomial (8:1) for data channel 3
0x20...0x3E	0x00		Not used
0x3F	0xXX		Check sum (addition of all bytes within this bank)

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AM34 - Absolute Multiturn Motor Feedback Encoder Standard Performance for Servo Motor and Drive

Bank 0x25: EDS Encoder data

Register	Value	Units	Description	Meaning
0x00	0x01		BiSS Profile 3 Version	1
0x01	0x01	Bank	Length of this profile	1
0x02...0x03	0x61XX		Profile identification BP3 (content also available in address 0x42 and 0x43)	XX
0x04	0x01		Feedback bit 1 low active error status nE	ERR bit low active
0x05	0x02		Feedback bit 2 low active warning status nW	WRN bit low active
0x06	0x14	ms	Maximum "power on delay" until position data available	20
0x07	0x00		Reserved	0
0x08	0x00		Encoder type	Rotary encoder
0x09	0x00		Position value	Not defined
0x0A	0x00	bit	Data length MULTITURN	0
	0x0C			12
0x0B	0x01		Data format MULTITURN	Left aligned
0x0C	0x14	bit	Data length COARSE	20
0x0D	0x01		Data format COARSE	Left aligned
0x0E	0x00	bit	Data length FINE	0
0x0F	0x00		Data format FINE	Right aligned
0x10...0x13	0x00001000		Number of distinguishable revolutions/periods	4096
0x14...0x17	0x00000100	PPR	Number of signal periods per revolution/ length of signal period	256
0x18...0x1B	0x00000100		Resolution factor per signal period (LSB of the interpolation)	256
0x1C...0x1F	0x00000043		CRC polynomial (32:1) 2)	67
0x20...0x23	0x00000000		CRC start value3)	0
0x24...0x25	0x0000	LSB/2	Absolute accuracy	0
0x26...0x27	0x0000	LSB/2	Repeat accuracy	0
0x28...0x29	0x0000	LSB/2	Angular speed/ speed depending accuracy	0
0x2A...0x2B	0x0000	LSB/2	Hysteresis	0
0x2C...0x2D	0x2710	rpm	Maximum revolution speed/ maximum speed	10000
0x2E...0x2F	0x0000	1/min2	Maximum angular acceleration/ maximum acceleration	0
0x30...0x31	0x00E9	°C	Minimum operating temperature = reg(value)-273_{dec}	-40
0x32...0x33	0x0184	°C	Maximum operating temperature = reg(value)-273_{dec}	115
0x34...0x35	0x1194	mV	Minimum operating voltage	4500
0x36...0x37	0x157C	mV	Maximum operating voltage	5500

Note on BiSS-C:

For the commands for adjusting the analog signals (0xB0), the digital adjustment (0xB2) and the eccentricity adjustment (0xB3), the encoder must be driven at a speed that is as constant as possible (300 rpm ... 1000 rpm).
Depending on the speed, a time must be observed during these adjustment processes during which no communication with the encoder should take place.
-> Duration in seconds: 0xB0 = 900/speed in rpm; 0xB2 = 1200/speed in rpm; 0xB3 = 15360/speed in rpm.

After the adjustment, the configuration must be saved:
-> Command 0x41 save the configuration.

Documents for BiSS-C and the EDS can be found on the following website:
https://biss-interface.com/c/downloads

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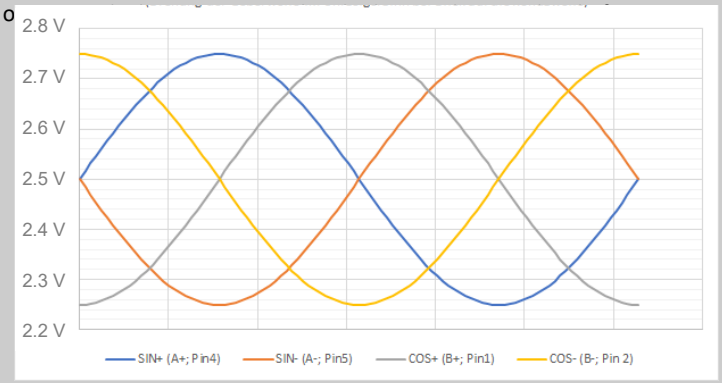
AM34 - Absolute Multiturn Motor Feedback Encoder Standard Performance for Servo Motor and Drive

TECHNICAL DATA
electrical interface Sin/Cos

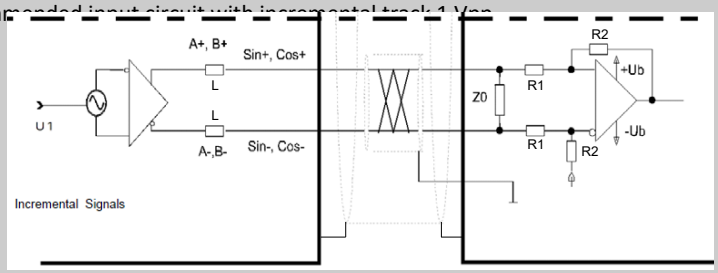
Analog output signals SIN/COS	
Output signal	**Description**
A+	Sine+ (SIN+)
A-	Sine- (SIN-)
GND	Signal grounds (analog/digital) internally connected
B+	Cosine (COS+)
B-	Cosine- (COS-)

Characteristics analogue output signals SIN/COS				
Symbol	**Parameter**	**Value**	**Tolerance**	**Unit**
P_n	Sine/Cosine periods per turn (360°)	256		#
$f()_{sin/cos}$	Frequency Analog	≤60		kHz
Vout()dc	Output Signal DC Level (typ. 2.5V DC)	50	±3	%VDD
Vout()ac	Output Signal AC Amplitude	250		mV
I()mx	Permissible Load Current	±30		mA
C()mx	Permissible Capacitive Load	≤50		pF
α()e,mx	Maximum Permissible Acceleration α()e = dω/dt for sine/cosine	≤200		10^6 rad/s^2
PH	Phase sine/cosine	90	±3	°

Signal o



Recomm



Dimensions:
L = 4.7µH , R1 = 10kΩ ,R1 = R2, Z0 = 120 Ω
U1 = 2.5 V ± 0.5V (relating to supply voltage).
Twisted pair wiring with ground shield on both sides recommended.

AM34 - Absolute Multiturn Motor Feedback Encoder Standard Performance for Servo Motor and Drive

TECHNICAL DATA electrical interface AB

Incremental output signals AB *(in preparation)*

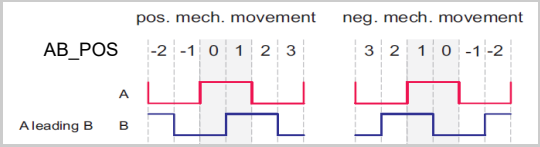
Output signal	Description
A+	A+ (TTL)
A-	A- (TTL)
GND	Signal grounds (analog/digital) internally connected
B+	B+ (TTL)
B-	B- (TTL)

Characteristics output signals AB

Characteristics incremental output signals AB

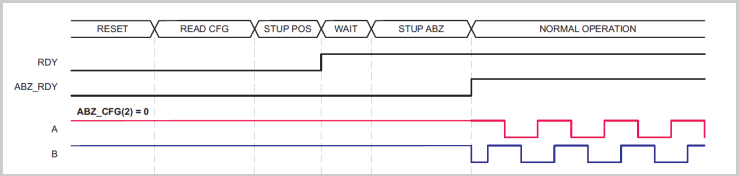
Symbol	Parameter	Value	Tolerance	Unit
P_n	AB periods per turn (360°)	1-4096		#
AB-HYS	AB hysteresis	0 / 0.044	(0 / 2 LSB)	°e
MTD	Minimum Transition Distance	100		nsec
$f()_{AB}$	Frequency incremental	≤960		kHz
Vout()hi	Output Signal Amplitude high	≥ 70		%VDD
Vout()lo	Output Signal Amplitude low	≤ 30		%VDD
I()mx	Permissible Load Current	±30		mA
C()mx	Permissible Capacitive Load	≤50		pF
α()e,mx	Maximum Permissible Acceleration α()e = dω/dt for A/B	≤200		10^6 rad/s^2
PH	Phase A/B	90	±40	°

AB signals for different mechanical and electrical directions of movement

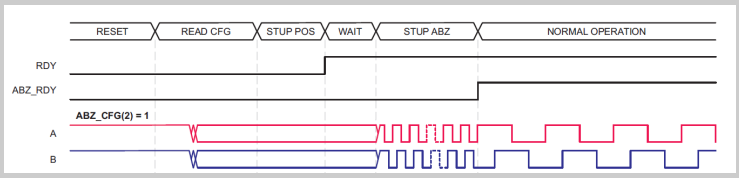


Startup behavior AB

AB = 11 during startup, until position found



AB counting from 0 position to actual position with programmed MTD



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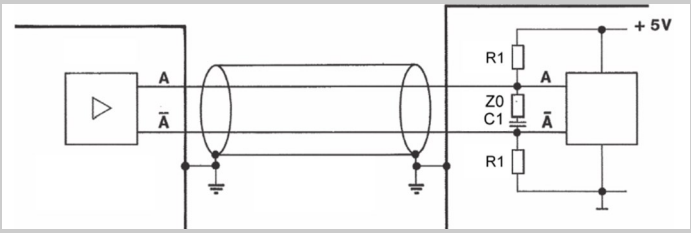
AM34 - Absolute Multiturn Motor Feedback Encoder Standard Performance for Servo Motor and Drive

TECHNICAL DATA
electrical interface AB

Recommended input circuit with incremental track - A/B signals



Dimensions:
R1 = 10kΩ ,C1 = 10nF, Z0 = 120 Ω
Twisted pair wiring with ground shield on both sides recommended.